

# IMPROVEMENT IN DOUBLY FED INDUCTION GENERATOR DURING FAULT USING CROWBAR CIRCUIT

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## ABSTRACT

*The performance of a 1.5 MV A wind power doublyfed induction generator (DFIG) under network fault, when the fault occurs the line voltage or current becomes 8 times to the normal rating, which can damage the converter which are connected to the rotor sideis studied in MATLAB-Simulink. The simulation network,consists of the DFIG analytical model, the detailed frequency converter model including passive crowbar protection. Simulation results show the transient behaviour of the doubly fed induction generator when a sudden voltage dip is introduced with and without the crowbar implemented.*

**Keywords:** DFIG, Grid Stability, Wind Turbine Technology, crowbar .

## I. INTRODUCTION

Wind power has become the world's fastest growingrenewable energy source. The many benefits of the wind energy are environmental protection, economic development, diversity of the supply, rapid spread, transference and technological innovation, industrial scale electricity in network and the fact is that the wind does not pollute, it is abundant, free and unlimited.

Thereare many benefits of using DFIG over general induction generators. DFIG can operate in generator/ motor mode for all four possible operation conditions. In DFIG a speed variation of  $\pm 30\%$  around synchronous speed can be obtained by the use of power convertor of 30% of nominal generated power. The DFIG is not necessarily to be magnetised from the power grid since it can be magnetised from rotor circuit to. The size of the convertor is not related to the total generator power but to the selected speed range and hence to the slip power.

Nowadays, there is an increasing requirement for wind farms to remain connected to the power system during faults, since the wind power lost might affect the system stability Therefore, the wind turbine behaviour during system performance and its influence in the system protection must be analyzed.The aim of this paper is to investigate and presents the transientsimulation analysis of a 1.5 MV A DFIG for wind power application under a three-phase network short circuit.

## II.DOUBLY-FED INDUCTION GENERATOR

For dynamic simulation purposes, these investigations are carried out based on well prepared Matlab simulation software's. The principle of the DFIG is that rotor windings are connected to the grid via slip rings and back-to-back voltage source converter that controls both the rotor and the grid currents. Thus rotor frequency differs from the grid frequency (50 Hz). By controlling the rotor currents by means of converter it is possible to adjust the active and reactive power fed to the grid from the stator independently of the generators turning speed. The control principle used is either the two-axis current vector control or Direct Torque Control (DTC). DTC has turned out to have better stability than current vector control especially when high reactive currents are required from the generator. The doubly-fed generator rotors are typically wound with from 2 to 3 times the number of turns of the stator. This means that the rotor voltages will be higher and currents lower. Thus in the typical  $\pm 30\%$  operational speed range around the synchronous speed the rated current of the converter is accordingly lower leading to a low cost of the converter. The drawback is that controlled operation outside the operational speed range is impossible because of the higher rated rotor voltage. In order to prevent high rotor voltages - and high currents resulting from these voltages - from destroying the IGBTs and diodes of the converter a protection circuit (called crowbar) is used. A doubly fed induction machine is a wound-rotor doubly-fed electric machine and has several advantages over a conventional induction machine in wind power applications. Firstly, as the rotor circuit is controlled by a power electronics converter, the induction generator is able to import and export reactive power. This has important consequences for power system stability and allows the machine to support the grid during severe voltage disturbances (low voltage ride through, LVRT). Secondly, the control of the rotor voltage and current enables the induction machine to remain synchronized with the grid while the wind turbine speed varies.

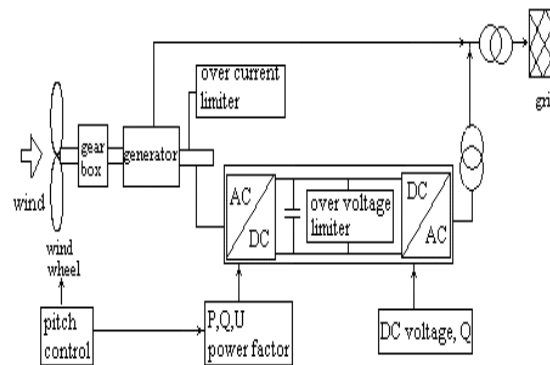


Figure 1.The block diagram of protection measure for FRT of DFIG WT.

## III. CROWBAR

The Sim Power Systems DFIG model does not include a crowbar protection. This has therefore been added, with some simplifications. The crowbar is made up of a symmetric three phase y-connected resistance. It is connected to the rotor through a controllable breaker. This is not the real case (in reality, the crowbar may be made up of one resistance fed through a switched rectifier bridge), but it may be sufficient for us to assess the overall impact of a crowbar protection on the LVRT. The breaker is normally open, but it is closed short circuiting the rotor

through the resistance if either the rotor current or the DC-link capacitor voltage become too high. At the same time the switching of the RSC is stopped. The value of the crowbar resistance is chosen according to as 20 times the rotor resistance. The choice of the crowbar resistance is important because, as we will see, it determines how much reactive power the DFIG will draw while the crowbar is inserted.

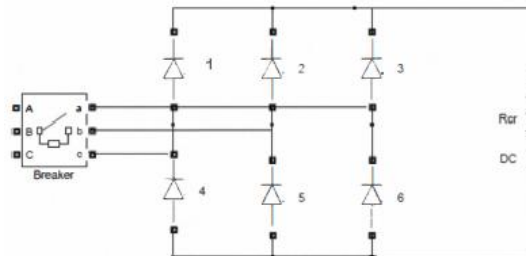


Figure 2. Crowbar scheme

#### IV.RESULTS FROM DFIGSIMULATIONS WITH FAULT AND WITHOUT CROWBAR

At the fault instant, the voltage at the DFIG generator terminal drop and it leads to a corresponding decrease of the stator and rotor flux in the generator. This results in reduction in the active power. As the stator flux decreases, the magnetization that has been stored in the magnetic field is released. Immediately after fault, the generator starts to absorb reactive power for its magnetization from the power system as shown below. When the voltage in poverty the network side converter is no longer able to transfer power to the rotor side converter therefore received the additional power will be borne by the capacitor voltage, which generates a rapid increase in the dc voltage converter.

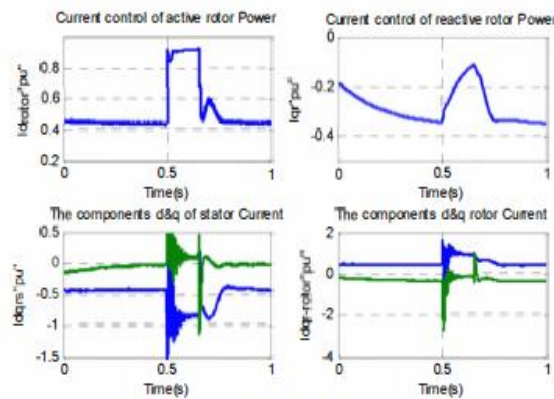


Figure 3. The active and reactive current and (d,q) current components

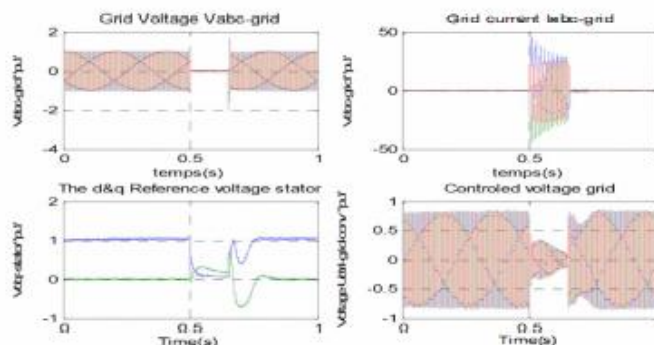


Figure 4. The three phase voltage and current

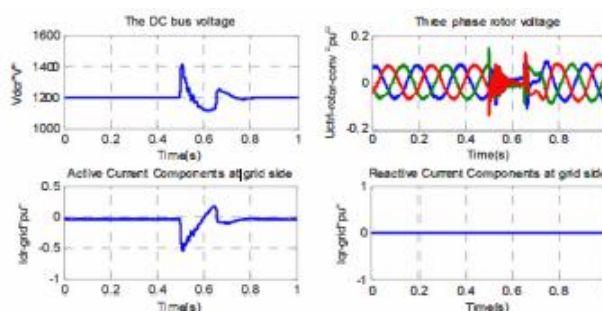


Figure 5. The DC voltage three phase rotor and (d,q) current components at the grid

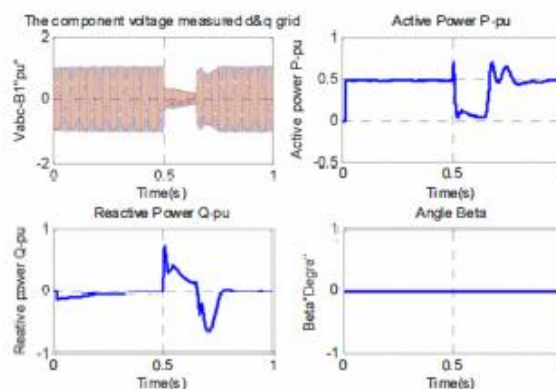


Figure 6. The active and reactive power

## V.RESULTS FROM DFIG SIMULATIONS WITH FAULT AND WITH CROWBAR

The simulation of the LVRT of a DFIG wind farm has been performed using the described crowbar protection. The results are shown below. Before the fault, the DFIG wind farm was in steady state with almost no reactive power. When the fault occurs, the crowbar protection is triggered, protecting the RSC which stops switching. The rotor current in the crowbar and the rotor windings decays and the DC link voltage increases slightly while the crowbar is connected. Notice that the crowbar disconnects and the RSC starts switching while the fault is still active, at about 70 ms after the fault. This is important since it allows the DFIG to feed reactive power (about 0.3 pu) into the network, increasing the voltage. This of course may have a positive

effect for the voltage stability of the system. The rotor current in the DFIG windings decreases, while the RSC current ( $I_{rot}$ ) is zero when the crowbar is active. The RSC voltage is then the voltage over the crowbar. The DC-link capacitor voltage does not increase much just after the fault. However, its increase is very high (2pu) when the fault is disconnected at 650 ms, even though the crowbar is correctly reinserted to limit the RSC current. This increase, as can be seen, is due to the fact that the DFIG absorbs active power just after the fault is disconnected. This clearly indicates the need for a chopper to be connected across the DC-link capacitor to limit its voltage. Finally notice that when the fault is disconnected, the DFIG absorbs reactive power, thus decreasing the voltage in the network. This is due to the fact that, being the crowbar still connected for a long time (because of the high DC-link voltage), the DFIG is actually a FSIG accelerating and thus drawing a lot of  $R=0.146$ .

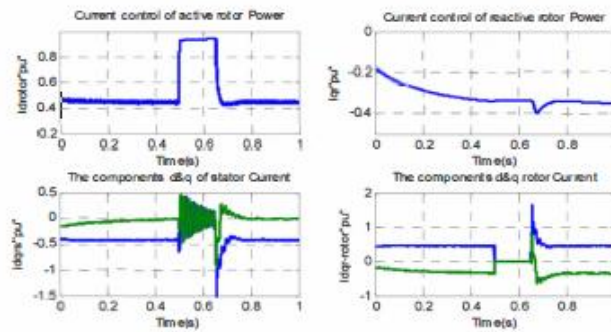


Figure 7. The active and reactive current and (d,q) current components

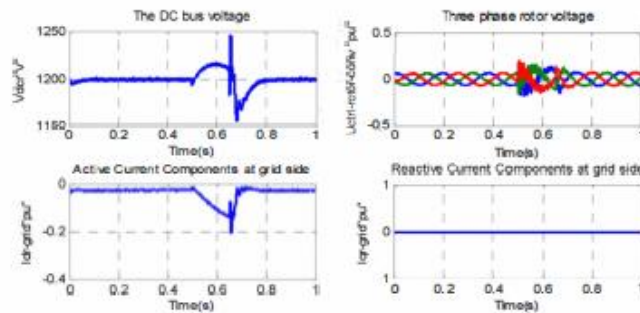


Figure 8. The DC voltage three phase rotor and (d,q) current components at the grid

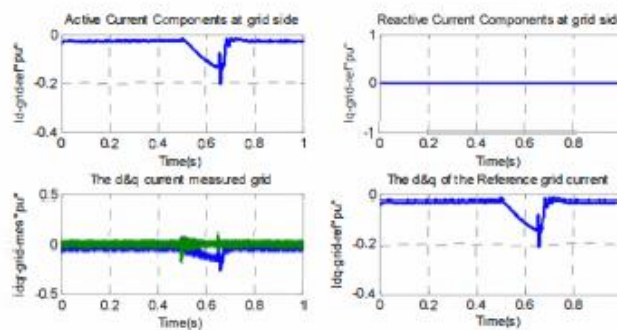


Figure 9. The active and reactive current and (d,q) current components



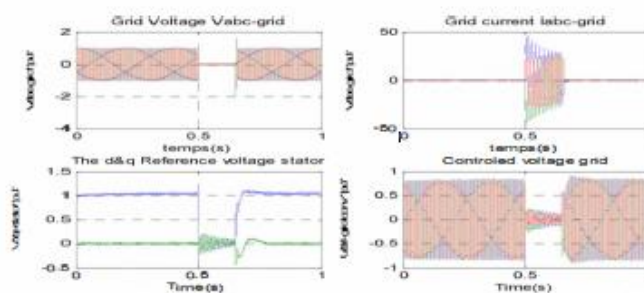


Figure 10. The three phase voltage and current

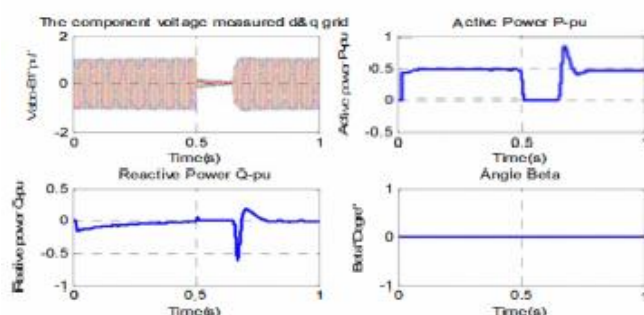


Figure 11. The active and reactive power

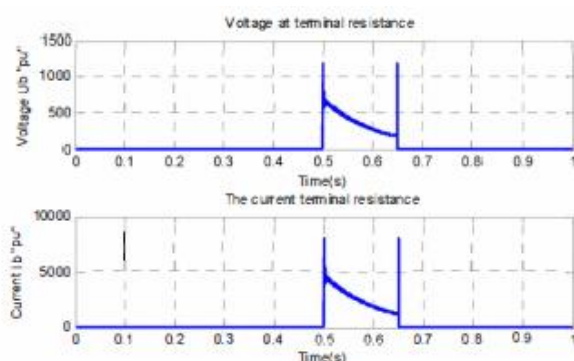


Figure 12. The current to the terminal of the resistance of the crowbar

## VI.EXPERIMENTAL SETUP

The 9MW wind farm is connected to a 25 kV network, viaa 66 KV/440V transformer. The transformer is rated 12 MV A. A resistive load of 500kw is connected at the wind farm. A high pass capacitor filter is used, the DFIG wind farm is connected to the 120 kV network through a 30 km 66 kV line and a 120/125 kV transformer.

## VII.CONCLUSIONS

The crowbar protectinavoides high rotor currents, high stator current and improvement in DC link voltage. During fault when crowbar is active the doubly fed induction generator act as a squirrel cage generator which consumes large amount of reactive power that's why we have to choose a proper resistance for crowbar circuit. So that it consumes less amount of reactive power and protects the circuit. Simulation results show the transient

behaviour of the doubly fed induction generator with and without the crowbar implemented when a sudden voltage dip is introduced.

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